

Math 412 Adventure sheet on the Orbit Stabilizer Theorem

Fix a group action of the group G on the set X .

DEFINITION: The **orbit** of an element $x \in X$ is the subset of X

$$O(x) := \{g \cdot x \mid g \in G\} \subseteq X.$$

DEFINITION: The **stabilizer** of an element $x \in X$ is the subgroup of G

$$\text{Stab}(x) = \{g \in G \mid g(x) = x\} \subset G.$$

ORBIT-STABILIZER THEOREM: *If a finite group G acts on a set X , then for every $x \in X$, we have*

$$|G| = |O(x)| \cdot |\text{Stab}(x)|.$$

A. Let D_4 be the symmetry group of the square. Consider the natural action of D_4 on the square with vertices $(\pm 1, \pm 1)$ by rotations and reflections.

- (1) Complete the following chart which records, for different points of the square, the orbit, stabilizer, and cardinalities of each.

$(x, y) \in \mathbb{R}^2$	$O(x, y)$	$\text{stab}(x, y)$	$\# O(x, y)$	$\# \text{stab}(x, y)$
$(0, 0)$				
$(1, 0)$				
$(1, 1)$				
$(1, \frac{1}{10})$				
$(\frac{1}{2}, \frac{1}{3})$				

- (2) Verify the orbit stabilizer theorem for each of the five points in your chart.

Solution.

- (1) We will use the notation $\{e, r, r^2, r^3, l_v, l_h, l_{(1,1)}, l_{(1,-1)}\}$, where l_v is the reflection on the line $x = 0$, l_h is the reflection on the line $y = 0$, $l_{(1,1)}$ is the reflection on the line $x = y$ and $l_{(1,-1)}$ is the reflection on the line $y = -x$.

$(x, y) \in \mathbb{R}^2$	$O(x, y)$	$\text{stab}(x, y)$	$\# O(x, y)$	$\# \text{stab}(x, y)$
$(0, 0)$	$\{(0, 0)\}$	D_4	1	8
$(1, 0)$	$\{(\pm 1, 0), (0, \pm 1)\}$	$\{e, l_h\}$	4	2
$(1, 1)$	$\{(\pm 1, \pm 1)\}$	$\{e, l_{(1,1)}\}$	4	2
$(1, \frac{1}{10})$	$\{(\pm 1, \pm \frac{1}{10}), (\pm \frac{1}{10}, \pm 1)\}$	$\{e\}$	8	1
$(\frac{1}{2}, \frac{1}{3})$	$\{(\pm \frac{1}{2}, \pm \frac{1}{3}), (\pm \frac{1}{3}, \pm \frac{1}{2})\}$	$\{e\}$	8	1

- (2) Easy: the number of elements in the orbit times the number of elements in the stabilizer is the same, always 8, for each point.

B. THE STABILIZER OF EVERY POINT IS A SUBGROUP. Assume a group G acts on a set X . Let $x \in X$.






- (1) Prove that the stabilizer of x is a **subgroup** of G .
 (2) Use the Orbit-Stabilizer theorem to prove that the cardinality of every orbit divides $|G|$.

- (3) Let G be a group of order 17 and let X be a set with 16 elements. Explain why there is no nontrivial action of G on X . [The trivial action is the one in which $g \cdot x = x$ for all $g \in G$ and all $x \in X$.]

Solution.

- (1) We need to show that $Stab(x) = \{g \in G \mid g \cdot x = x\}$ is a subgroup of G . It suffices to check:
- (a) $Stab(x)$ is non-empty; this is easy since $e_G \cdot x = x$ (by definition of action), so $e_G \in Stab(x)$.
 - (b) If $a, b \in Stab(x)$, then $ab \in Stab(x)$. Also pretty easy: take arbitrary $a, b \in Stab(x)$. We compute $(a \circ b) \cdot x = a \cdot (b \cdot x)$ by definition of action. Since $b \cdot x = x$, this becomes $(a \circ b) \cdot x = a \cdot (b \cdot x) = a \cdot x$; and since $a \cdot x = x$, we conclude that $(a \circ b) \cdot x = x$. Thus $a \circ b \in Stab(x)$.
 - (c) if $a \in Stab(x)$, then $a^{-1} \in Stab(x)$. For this, take arbitrary $a \in Stab(x)$. This means $a \cdot x = x$. Apply a^{-1} to both sides to get $a^{-1} \cdot (a \cdot x) = a^{-1} \cdot x$. By definition of action, $a^{-1} \cdot (a \cdot x) = (a^{-1} \circ a) \cdot x = e \cdot x = x$. So we have $a^{-1} \cdot x = x$, and $a^{-1} \in Stab(x)$.
- QED.
- (2) This is clear: $|O(x)|$ divides $|G|$ since $|G| = |O(x)| \times |Stab(x)|$.
- (3) Since 17 is prime, the only divisors of $|G|$ are 1 and 17. So any orbit of any G action can only have size 1 or 17. Since in this case, X has only 16 points total, no orbit can have 17 points! So all orbits have one point. This means $g \cdot x = x$ for all g and all x . The only such action is the trivial action.

C. SYMMETRY GROUPS OF PLATONIC SOLIDS. There are exactly five convex regular solid figures in \mathbb{R}^3 .

Polyhedron		Vertices	Edges	Faces
tetrahedron		4	6	4
cube		8	12	6
octahedron		6	12	8
dodecahedron		20	30	12
icosahedron		12	30	20

Each is constructed by congruent regular polygonal faces with the same number of faces meeting at each vertex. The chart describes each of these platonic solids. Each platonic solid has a symmetry group which acts naturally on the solid. In particular, each symmetry group also acts on the set of vertices, the set of edges and the set of faces, of the corresponding solid. By analyzing these three actions, we can better understand the symmetry group of each solid.

For each of the 5 platonic solids, complete the following chart:

Action	# orbit	# stab	$ G $
on Faces			
on edges			
on vertices			

For each of the three actions, does it matter which point $x \in X$ (i.e., which face, edge, or vertex) you use to compute the orbit? Why is the order of the stabilizer the same for each $x \in X$ in each of the three actions? Is this true in general for a group acting on a set? What is special in this case?

Solution.

- (1) For the symmetry group of the cube, we have:

Action	# orbit	# stab	$ G $
on Faces	6	4	24
on edges	12	2	24
on vertices	8	3	24

(2) For the symmetry group of the tetrahedron we have:

Action	# orbit	# stab	$ G $
on Faces	4	3	12
on edges	6	2	12
on vertices	4	3	12

Note that here, it is a bit tricky to find the stabilizer of an edge, but since we know there are 2 elements in the stabilizer from the Orbit-Stabilizer theorem, we can look.

(3) For the Octahedron, we have

Action	# orbit	# stab	$ G $
on Faces	8	3	24
on edges	12	2	24
on vertices	6	4	24

(4) For the symmetry group of the dodecahedron, we have:

Action	# orbit	# stab	$ G $
on Faces	12	5	60
on edges	30	2	60
on vertices	20	3	60

(5) For the symmetry group of the icosahedron, we have:

Action	# orbit	# stab	$ G $
on Faces	20	3	60
on edges	30	2	60
on vertices	12	5	60

D. Consider the group Cube of symmetries of the cube.

- (1) Observe that Cube acts on the set of 4 diagonals (from one vertex to its opposite) of the cube.
- (2) Show that this action is faithful.¹
- (3) Show that Cube is isomorphic to \mathcal{S}_4 .²
- (4) Conclude that the orders of the elements in Cube are exactly 1, 2, 3, 4, and that Cube is generated by two elements.

Solution.

- (1) A symmetry must take a diagonal to a diagonal; it is clear that this is compatible with composition.

¹Hint: Label the diagonals as 1, 2, 3, 4. Note that every face has one vertex on each diagonal. For each face, list the diagonal of each vertex, counterclockwise, starting with 1. Note that each face has a different list.

²Hint: Use the homomorphism $\text{ad} : G \rightarrow \text{Bij}(X)$ from the last worksheet.

- (2) Following the hint, once we label the diagonals, every face is determined by the order in which the diagonals meet its vertices. Thus, if an element of the group fixes all four diagonals, then it fixes all of the faces, so it can only be the identity.
- (3) By the last part, we obtain an injective homomorphism from Cube to S_4 . Since these groups have the same order, this map must be bijective.
- (4) This follows from the fact that these statements hold in S_4 .

E. THE PROOF OF THE ORBIT-STABILIZER THEOREM: Let G act on X . Fix a point $x \in X$.

- (1) Show that there is a surjective map of sets $G \rightarrow O(x)$ sending each $g \in G$ to $g \cdot x$.
- (2) Show that g and h have the same image under this map if and only if $g^{-1}h \in \text{Stab}(x)$.
- (3) For each $g \cdot x \in O(x)$, show that the set of elements in G mapping to $g \cdot x$ is the coset Kg where $K = \text{Stab}(x)$.
- (4) Show that this map induces a bijection between the set $G/\text{Stab}(x)$ of cosets of $\text{Stab}(x)$ in G and the orbit $O(x)$.
- (5) Prove the Orbit Stabilizer Theorem.

Solution.

- (1) Given any $y \in O(x)$, $y = g \cdot x$ for some g , so y is in the image of our map.
- (2) Given any $g, h \in G$, $g \cdot x = h \cdot x$ if and only if $x = (g^{-1}h) \cdot x$, or equivalently $g^{-1}h \in \text{Stab}(x)$.
- (3) Given $g \in O(x)$, we have shown that for each $h \in G$, $h \cdot x = g \cdot x$ if and only if $h^{-1}g \in \text{Stab}(x)$, which by definition is equivalent to $h \in Kg$.
- (4) We have already showed that two elements g and h have the same image if and only if $Kg = Kh$, so the map $G/\text{Stab}(x) \rightarrow O(x)$ given by $\text{Stab}(x) \cdot g \mapsto g \cdot x$ is well-defined and injective. We have also already shown that this map is surjective.
- (5) Our bijection shows that $|O(x)| = [G : \text{Stab}(x)]$. The Orbit-Stabilizer theorem now follows by Lagrange's Theorem.

F. LINEAR ACTIONS. Consider the action of $GL_2(\mathbb{R})$ on \mathbb{R}^2 by matrix multiplication (where elements of \mathbb{R}^2 are written as columns).

- (1) Describe the action in mathematical symbols and prove it is really an action.
- (2) What is the stabilizer of the point $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$?
- (3) What is the orbit of the point $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$?

Solution.

- (1) For $A \in GL_2(\mathbb{R})$ and $\begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2$, we have $A \cdot \begin{bmatrix} x \\ y \end{bmatrix} = A \begin{bmatrix} x \\ y \end{bmatrix}$. It is an action because $I_2 \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$ and $A \cdot (B \cdot \begin{bmatrix} x \\ y \end{bmatrix}) = A(B \begin{bmatrix} x \\ y \end{bmatrix}) = (AB) \begin{bmatrix} x \\ y \end{bmatrix}$, by the associativity of matrix multiplication. So the two axioms of a group action are satisfied.
- (2) What $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ stabilize $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$? Since $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ c \end{bmatrix}$, a necessary and sufficient condition is that $\begin{bmatrix} a \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$. So the stabilizer of $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is the subgroup of matrices $\left\{ \begin{bmatrix} 1 & b \\ 0 & d \end{bmatrix} \mid b, d, \in \mathbb{R} \right\}$.

(3) The orbit of $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ under matrix multiplication is $\mathbb{R}^2 \setminus \vec{0}$. Indeed, we can get an arbitrary non-zero $\begin{bmatrix} x \\ y \end{bmatrix}$ by multiplying $\begin{bmatrix} x & b \\ y & d \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$. Note that as long as $\begin{bmatrix} x \\ y \end{bmatrix}$ is not the zero vector, we can always find $b, d \in \mathbb{R}$ such that the matrix $\begin{bmatrix} x & b \\ y & d \end{bmatrix}$ is invertible.

G. SYMMETRY GROUPS OF PLATONIC SOLIDS AGAIN.

- (1) Show that the symmetry group of the tetrahedron is isomorphic to \mathcal{A}_4 .
- (2) Show that the symmetry group of the octahedron is isomorphic to \mathcal{S}_4 .
- (3) Can you compute the symmetry groups of the dodecahedron and the icosahedron?

Solution.

- (1) Inspired by our calculation of the symmetry group of the cube, we look for a set of four elements for this group to act on. An obvious choice is the set of faces. It is clear that this action is faithful: if a symmetry of the tetrahedron fixes all four faces, it fixes the whole tetrahedron. We then get an injective homomorphism from $\text{Tet} \hookrightarrow \mathcal{S}_4$. We know $|\text{Tet}| = 12$ and $|\mathcal{S}_4| = 24$, so this is not surjective.

We can show directly that the image consists of even permutations. For each vertex, there are two 120° rotations. These fix one face and cycle around the others, so these give the 8 three cycles. Also, there are three 180° rotations that switch two pairs of faces. These are the three pairs of disjoint 2-cycles. This plus the identity makes for all twelve elements.

- (2) The argument is similar to that for the cube, except let Oct act on the set of *pairs of opposite faces* of the octahedron. We challenge you to fill in the details!
- (3) They are both \mathcal{A}_5 ! We challenge you to prove it!

H. REPRESENTATIONS OF A GROUP. A REPRESENTATION of a group G on a vector space V is a group homomorphism $G \longrightarrow GL(V)$ to the set of bijective linear transformations $V \longrightarrow V$.

- (1) Explain why a group representation is equivalent to an action of G on V where for each $g \in G$, $\text{ad}(g)$ is a linear transformation.
- (2) Show that a group representation is a faithful action if and only if $G \longrightarrow GL(V)$ is injective.
- (3) Give an example of a representation of D_n on \mathbb{R}^2 .

Solution.

- (1)
- (2) We have shown this in the previous worksheet in a more general setting.
- (3) We have essentially already seen this example in Problem Set 8:

$$r \mapsto \begin{pmatrix} \cos\left(\frac{2\pi}{n}\right) & -\sin\left(\frac{2\pi}{n}\right) \\ \sin\left(\frac{2\pi}{n}\right) & \cos\left(\frac{2\pi}{n}\right) \end{pmatrix} \text{ and send the reflection about the } y\text{-axis to } \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}.$$